

### CS20a: NP problems

- The SAT problem
- Graph theory




---

---

---

---

---

---

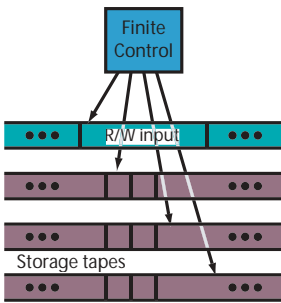
---

---

---

---

### Time-bounded TMs



- All tapes are 2-way infinite
- M is DTIME(T(n)) if
  - M is deterministic
  - For any input of length n, M takes at most T(n) steps
- M is NTIME(T(n))
  - Nondeterministic case




---

---

---

---

---

---

---

---

---

---

### NP problems

- A problem is *in NP* if it can be decided yes/no by a nondeterministic TM in  $O(n^c)$  steps
  - $n$  is the length of the input
  - $c$  is a constant
- How long does it take to decide a problem in NP?
  - It takes  $O(n^c)$  time to explore each possible nondeterministic choice
  - There are an exponential number of choices
  - So it takes  $O(2^n)$  time worst case
- How long does it take to verify an NP execution?
  - There are  $O(n^c)$  steps of size  $O(n^c)$
  - So it takes  $O(n^{2c})$  time




---

---

---

---

---

---

---

---

---

---

### CNF satisfiability

- A propositional formula is in *conjunctive normal form* (CNF) if it is a conjunction of disjunctions of literals.
- A *literal* is a propositional letter, or the negation of a propositional letter.
- Every propositional formula can be represented in CNF.

$$\begin{aligned}
 & (A \vee \neg B \vee C) \\
 \wedge & (D \vee \neg B \vee \neg C) \\
 \wedge & (\neg A \vee B \vee E \vee \neg F) \\
 & \vdots \\
 \wedge & (E \vee F \vee \neg D \vee A \vee \neg B)
 \end{aligned}$$




---

---

---

---

---

---

---

---

---

---

### Satisfiability algorithm

- CNF should make the decision problem easier, since there is only conjunction, disjunction, negation
- An algorithm in NP
  - *Guess a truth assignment*
  - *Verify the assignment*
- An algorithm in P
  - *Must be deterministic (no "guessing")*
  - *Just figure out if the formula is true*




---

---

---

---

---

---

---

---

---

---

### Building an algorithm for 2SAT

- 2SAT: each clause has at most two literals  $A_1, \neg A_2, (A_3 \vee A_4), (A_5 \vee \neg A_6), \dots$
- **Algorithm**
  - Consider a clause  $(l \vee l')$
  - Rewrite the clauses as implications  $(\neg l \Rightarrow l') \wedge (l \Rightarrow l')$
  - Draw a graph
  - The formula is unsatisfiable iff there are two paths
    - \*  $l_1 \Rightarrow \dots \Rightarrow A$
    - \*  $l_1 \Rightarrow \dots \Rightarrow \neg A$




---

---

---

---

---

---

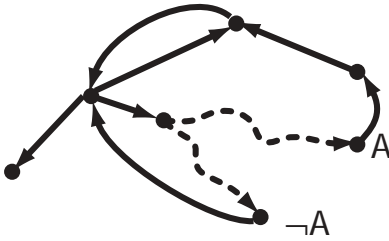
---

---

---

---

### 2SAT graph



If this page displays slowly, try turning off the "smooth line art" option in Acrobat, under Edit > Preferences.

---

---

---

---

---

---

---

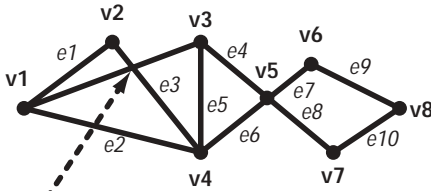
---

---

---

### Graph theory

- A graph is a set of points (*vertices*) that are interconnected by a set of lines (*edges*)



This is not a vertex



If this page displays slowly, try turning off the "smooth line art" option in Acrobat, under Edit > Preferences.

---

---

---

---

---

---

---

---

---

---

### Some common graphs



If this page displays slowly, try turning off the "smooth line art" option in Acrobat, under Edit > Preferences.

---

---

---

---

---

---

---

---

---

---

### Formal definition of graphs

- A graph  $G$  is defined as a pair  $G = (V, E)$  where
  - $V$  is a set of vertices
  - $E$  is a set of edges  $(v_i, v_j), \dots$
- $n = |V|$  is the size of the graph
- $|E|$  is the number of edges




---

---

---

---

---

---

---

---

---

---

### Graph definitions

- For any edge  $e = (v_i, v_j)$ , where  $(v_i, v_j) \in E$ ,
  - the edge  $e$  is *incident with* vertices  $v_i$  and  $v_j$
  - the vertices  $v_i$  and  $v_j$  are *adjacent*.
  - the *degree*  $d(v)$  of a vertex  $v$  is the number of edges that are incident to it.




---

---

---

---

---

---

---

---

---

---

### A simple theorem

**Theorem** The number of vertices of odd-degree in a finite graph is even.

**Proof** Note that if we add up all the degrees, we get twice the number of edges.

$$\sum_i d(v_i) = 2 \cdot |E|$$

Since the rhs is even, so is the number of vertices with odd degree.




---

---

---

---

---

---

---

---

---

---

### Path definitions

- A *subgraph* of  $G$  is a graph obtained by removing some edges and vertices from  $G$ .
- A *path* from  $v_1$  to  $v_n$  is a sequence  $P = v_1, e_1, \dots, e_{n-1}, v_n$  such that  $e_i = (v_i, v_{i+1})$
- If  $v_n = v_1$ , we say the path is a *cycle*, or *circuit*
- If each vertex appears only once, the path is *simple*.




---

---

---

---

---

---

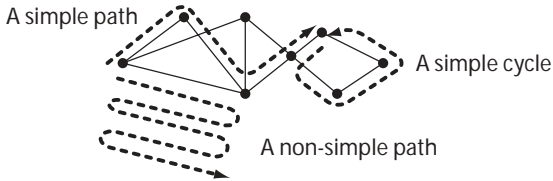
---

---

---

---

### Path example




---

---

---

---

---

---

---

---

---

---

### Connected components

- Two vertices  $v_i, v_j$  are *connected* if there is a path from  $v_i$  to  $v_j$
- The *connected components* of a graph are a partition  $V_1, V_2, \dots, V_k \subseteq V$  in which all vertices are connected.
- A *connected* graph has one component, otherwise it is *disconnected*
- An *articulation point* is a vertex  $v$  whose removal disconnects the graph.




---

---

---

---

---

---

---

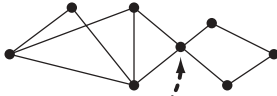
---

---

---

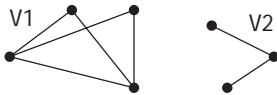
### Graph components

A connected graph



Articulation point

A disconnected graph



If this page displays slowly, try turning off the "smooth line art" option in Acrobat, under Edit > Preferences

---

---

---

---

---

---

---

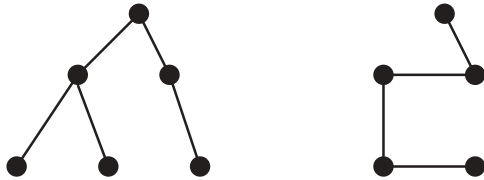
---

---

---

### Trees

- A tree is a connected graph with no cycles
- A forest is a set of trees



If this page displays slowly, try turning off the "smooth line art" option in Acrobat, under Edit > Preferences

---

---

---

---

---

---

---

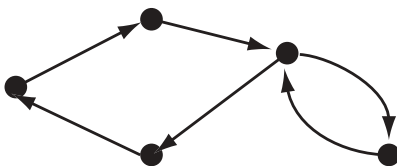
---

---

---

### Directed graphs

- A directed graph assigns a direction to the edges



If this page displays slowly, try turning off the "smooth line art" option in Acrobat, under Edit > Preferences

---

---

---

---

---

---

---

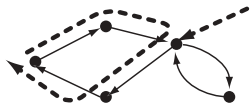
---

---

---

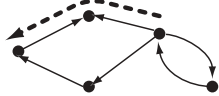
### Paths, cycles

A directed cycle

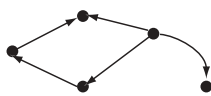


An articulation point

An undirected path



An acyclic graph



---

---

---

---

---

---

---

---

---

---

### Connected components

- A *directed* graph  $G$  is defined as a pair  $G = (V, E)$  where
  - $V$  is a set of vertices
  - $E$  is a set of edges  $(v_i \rightarrow v_j), \dots$
- Two vertices  $v_i, v_j$  are *strongly connected* iff there is a directed path from  $v_i$  to  $v_j$ , **and** a directed path from  $v_j$  to  $v_i$ .
- Two vertices  $v_i, v_j$  are *weakly connected* iff there is an undirected path from  $v_i$  to  $v_j$
- Use these to define *strongly-connected* and *weakly-connected* components.



---

---

---

---

---

---

---

---

---

---

### Graph algorithms: Depth-First-Search (DFS)

- DFS does the following:
  - Assigns a unique number to each vertex
  - Forms a spanning tree (called the DFS spanning tree)
- Basic algorithm
  - We need a stack of edges (initially empty)
  - A counter  $c$  (initially 1)



---

---

---

---

---

---

---

---

---

---

### DFS algorithm

- Choose an arbitrary vertex  $v$ , assign it the number 0, and push all edges incident with  $v$
- **While** the stack is not empty
  - Pop an edge  $(v_i, v_j)$  from the stack
  - The edge  $v_i$  already has a number
  - **If**  $v_j$  is not assigned a number
    - \* Assign  $v_j$  the number  $c$
    - \* Increment  $c$
    - \* Push all edges incident with  $v_j$




---

---

---

---

---

---

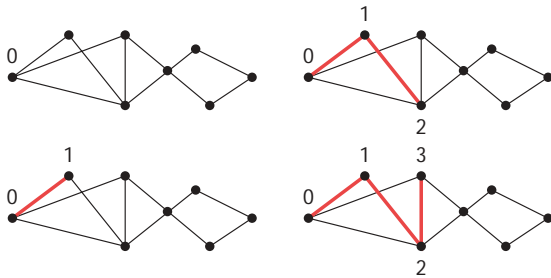
---

---

---

---

### DFS: Initial search



If this page displays slowly, try turning off the "smooth line art" option in Acrobat, under Edit > Preferences

---

---

---

---

---

---

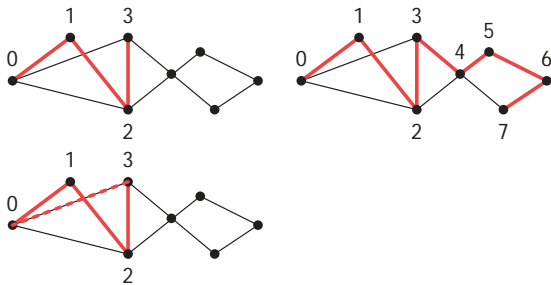
---

---

---

---

### DFS: Backtracking



If this page displays slowly, try turning off the "smooth line art" option in Acrobat, under Edit > Preferences

---

---

---

---

---

---

---

---

---

---



**Transitive case (part 1)**

- Let  $(u_1, v_1) \equiv (u_2, v_2)$  and  $(u_2, v_2) \equiv (u_3, v_3)$
- Let  $c_1, c_2$  be the two cycles
- Assume  $u_1, u_2, v_2, u_1$  occur in that order around  $c$
- Let  $x$  be the first vertex on the segment of  $c$  from  $u_1$  to  $u_2$  that also lies on  $c_2$
- Let  $y$  be the first vertex on the segment of  $c$  from  $v_1$  to  $v_2$  that also lies on  $c_2$




---

---

---

---

---

---

---

---

---

---

**Transitive case (part 2)**

- $x \neq y$  since  $c$  is simple
- Let  $p$  be the path fro  $x$  to  $y$  containing  $(u_1, v_1)$
- Let  $p'$  be the path from  $x$  to  $y$  containing  $(u_3, v_3)$
- Then  $p$  and  $p'$  intersect only in  $x, y$  and form a simple cycle and form a simple cycle containing  $(u_1, v_1)$  and  $(u_3, v_3)$




---

---

---

---

---

---

---

---

---

---

**Articulation points**

The equivalence classes of  $\equiv$  are called the *biconnected components*.

**Theorem** The vertex  $a$  is an articulation point iff  $a$  is contained in at least two biconnected components.

**Proof**

- If  $a$  disconnects the graph, then there are  $u, v$  such that every path from  $u$  to  $v$  goes through  $a$ . Then  $(u, a)$  and  $(a, v)$  can't lie on a simple cycle.
- Suppose  $(u, a) \neq (a, v)$ . Then all paths from  $u$  to  $v$  must go through  $a$ .




---

---

---

---

---

---

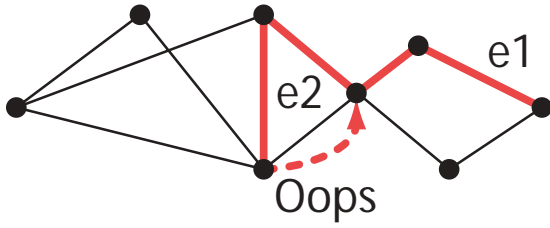
---

---

---

---

### Articulation points




---

---

---

---

---

---

---

---

---

---



### Using DFS to get biconnected components

**Theorem** Let  $(u, v)$  and  $(v, w)$  be two adjacent edges in a DFS tree of  $G$ . Then  $(u, v) \equiv (v, w)$  iff there is a back-edge from some descendent of  $w$  to some ancestor of  $u$ .

**Proof**

- If there is a back-edge from some descendent of  $w$  to some ancestor of  $u$ , then there is a simple cycle.
- Suppose  $(u, v) \equiv (v, w)$ . Then there is a simple cycle containing them. The DFS tree rooted at  $w$  must contain a back-edge because it has to get to  $u$ .

---

---

---

---

---

---

---

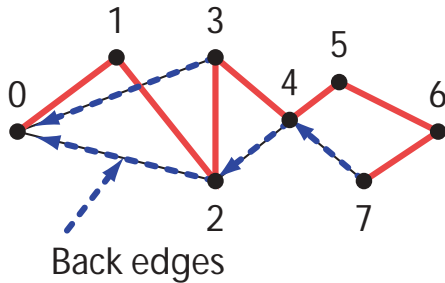
---

---

---



### DFS backedges




---

---

---

---

---

---

---

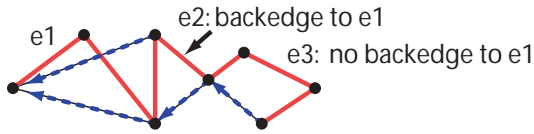
---

---

---



### DFS biconnected components



If this page displays slowly, try turning off the "smooth line art" option in Acrobat, under Edit Preferences.

---

---

---

---

---

---

---

---

---

---

### Solving 2SAT

- We can define DFS for *directed graphs*
  - Follow edges only in the forward direction
- Use DFS to determine strongly-connected components
  - Strongly-connected component
    - For each  $u, v$ , there is a path from  $u$  to  $v$ , and from  $v$  to  $u$



If this page displays slowly, try turning off the "smooth line art" option in Acrobat, under Edit Preferences.

---

---

---

---

---

---

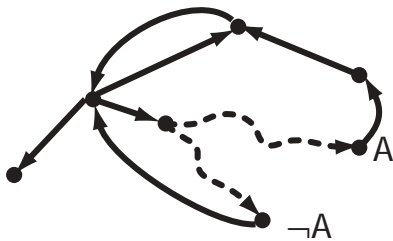
---

---

---

---

### 2SAT graph



If this page displays slowly, try turning off the "smooth line art" option in Acrobat, under Edit Preferences.

---

---

---

---

---

---

---

---

---

---

## 2SAT solution

- The formula is satisfiable iff there is a strongly-connected component that contains A and not A for some letter A
  - If it does, then A implies not A and not A implies A (contradiction)
  - If not, we have to define a satisfying assignment (next time)



---

---

---

---

---

---

---

---