

BARYCENTRIC COORDINATES

CS 176 WINTER 2011

1

BARYCENTRIC COORDINATES

Interpolation

- given data at sites, interpolate smoothly and intuitively “in between”
- easy over simplices: linear
- more general shapes needed
 - morphing, shape deformation, attribute interpolation, physical modeling, and on and on and on

CS 176 WINTER 2011

2

BASIC PRINCIPLES

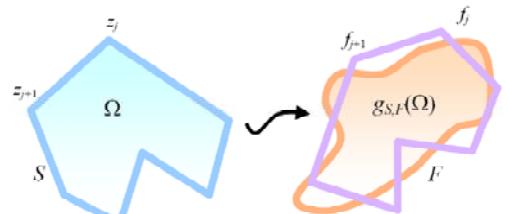
Data on boundary; extend

- as affine combination:
- if $p = \sum_{j=1}^n k_j(p)P_j$ then $f(p) = \sum_{j=1}^n k_j(p)f(P_j)$
- desirables
 - constant precision: $\sum k_j(x) = 1$
 - linear precision: $\sum k_j(x) x_j = x$
 - convex: many choices; concave: few...

CS 176 WINTER 2011

3

BASIC SETUP: CAGE



- from now on, we'll focus on Weber/Ben-Chen/Gotsman's method

CS 176 WINTER 2011

4

PLANAR CASE

Treat everything in complex plane

- tools from complex analysis...
- given source and target polygon
 $\{z_j\}_{j=1..n} \subset \mathbb{C}, \{f_j\}_{j=1..n} \subset \mathbb{C}, k_j: \mathbb{C} \rightarrow \mathbb{C}$

$$g_{S,F}(z) = \sum k_j(z) f_j$$
- desirables:

$$\sum k_j(z) = 1 \quad \sum k_j(z) z_j = z$$

CS 176 WINTER 2011

5

PROPERTIES

Complex barycentric interpolation

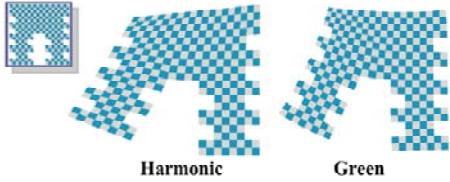
- preserve similarities
- distinction with real coeffs?
 - preserve affine transformation iff

$$\sum \bar{k}_j(z) z_j = z$$
 - not actually desirable... why?

CS 176 WINTER 2011

6

REAL VS. COMPLEX



- Affine transform not quite pleasing...

CS 176 WINTER 2011

7

TRADE-OFF

Must give up something...

- not interpolating anymore

How to find such functions?

- study continuous setting

$$\oint_S k(w,z) dw = 1 \quad \oint_S k(w,z) w dw = z$$

$$g_{S,f}(z) = \oint_S k(w,z) f(w) dw$$

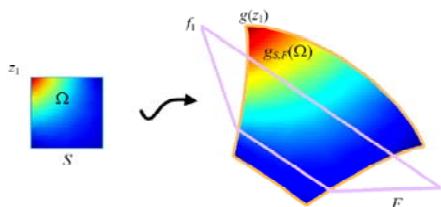


CS 176 WINTER 2011

8

NOT AN INTERPOLATION

Visualize one coordinate function



CS 176 WINTER 2011

9

CAUCHY FORMULA

Holomorphic functions

- Cauchy kernel: $C(w,z) = \frac{1}{2\pi i} \frac{1}{w-z}$

$$h(z) = \frac{1}{2\pi i} \oint_S C(w,z) h(w) dw$$

- integral version of *mean value theorem*

- recover value from average of boundary

- Cauchy coordinates:

$$g_{S,f}(z) = \frac{1}{2\pi i} \oint_S \frac{f(w)}{w-z} dw$$

CS 176 WINTER 2011

10

$$g_{S,f}(z) = \frac{1}{2\pi i} \oint_S \frac{f(w)}{w-z} dw$$

Only need data on boundary!

- apply to polygon

$$g_{S,f}(z) = \frac{1}{2\pi i} \sum \int_e \frac{f(w)}{w-z} dw$$

- define f linearly along edge

- grind out integrals...

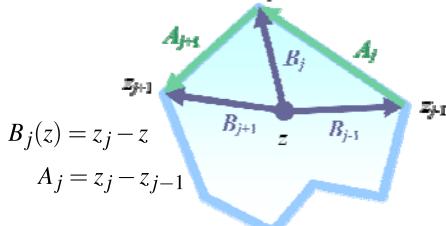
$$g_{S,f}(z) = \sum C_j(z) f_j$$

CS 176 WINTER 2011

11

RESULTING FORMULAS

$$C_j(z) = \frac{1}{2\pi i} \left(\frac{B_{j+1}(z)}{A_{j+1}} \log \left(\frac{B_{j+1}(z)}{B_j(z)} \right) - \frac{B_{j-1}(z)}{A_j} \log \left(\frac{B_j(z)}{B_{j-1}(z)} \right) \right)$$



CS 176 WINTER 2011

12

EXAMPLES



CS 176 WINTER 2011

13

PROPERTIES

Best holomorphic function?

- it doesn't interpolate; is it "best"?
 - closest to given boundary data
 - stick with C_j but use "virtual" poly.
- $$g_U(z) = \sum C_j(z)u_j$$
- minimize functional to find best poly.
- $$\min_U E_S(g_U)$$

CS 176 WINTER 2011

14

SZEGÖ COORDINATES

Optimize "fit"

$$E_S(g_U) = \oint_S |g_U(w) - f(w)|^2 dw$$

- need C_j on boundary...
- define through limit
- do point collocation (sample boundary)

$$E_S(g_U) = |Cu - f_S|^2$$

matrix with sampled C_j as columns

LSQ problem

CS 176 WINTER 2011

15

SOLUTION

Pseudo inverse

$$u = C^+ f_S = (C^* C)^{-1} C^* f_S$$

- size is number of vertices (small)
- $\overset{\text{Szegö}}{g}_{S,f}(z) = \sum G_j(z)f_j$

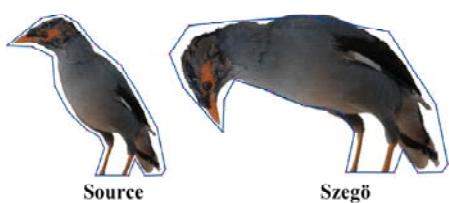
- letting H be sampling operator:

$$f_S = HF \quad u = C^+ f_S = MF \quad G_j(z) = \sum_{j=1}^{j=n} C_i(z)M_{i,j}$$

CS 176 WINTER 2011

16

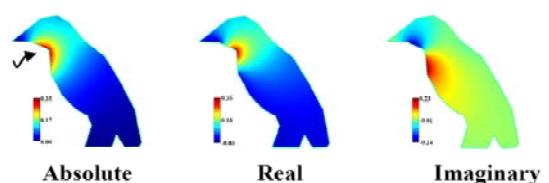
EXAMPLE



CS 176 WINTER 2011

17

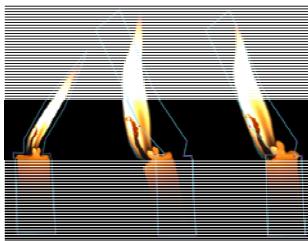
VISUALIZATION



CS 176 WINTER 2011

18

COMPARISON



CS 176 WINTER 2011

19

ANOTHER COMPARISON

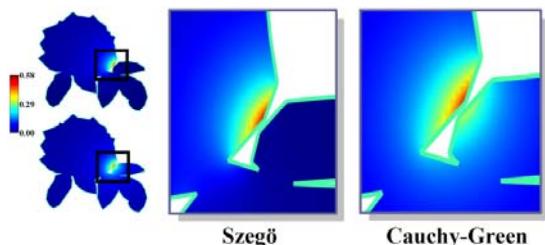


Cauchy-Green vs Szegö

CS 176 WINTER 2011

20

VISUALIZATION



CS 176 WINTER 2011

21

POINT - TO - POINT

Simplify UI

- just specify landmarks
- underconstrain (typically)
- add fairness constraint

$$E_S^{\text{smooth}}(g) = \oint_S |g''(w)|^2 dw$$

$$E_S^{\text{pts}}(g) = \sum_{i=1}^{i=p} |g(r_i) - f_i|^2$$

CS 176 WINTER 2011

22

P2P COORDINATES

Joint minimization

$$E_S^{\text{P2P}}(g) = E_S^{\text{pts}}(g) + \lambda^2 E_S^{\text{smooth}}(g)$$

- point collocation...

$$E_S^{\text{P2P}}(g) = \|C_u - f_s\|^2 + \|\lambda D\|^2 \quad N = \left(\frac{C}{\lambda D} \right)_{i=1, \dots, p}^+$$

$$g_{S,F}^{\text{P2P}}(z) = \sum_{i=1}^p P_i(z) f_i \quad P_i(z) = \sum_{j=1}^n C_j(z) N_{j,i}$$

CS 176 WINTER 2011

23

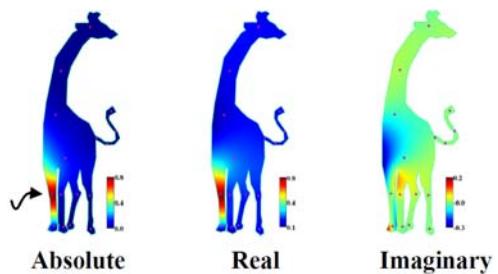
EXAMPLE



CS 176 WINTER 2011

24

VISUALIZATION



CS 176 WINTER 2011

25

EXAMPLE



CS 176 WINTER 2011

26

VIDEO

Complex Barycentric Coordinates with
Applications to Planar Shape Deformation

Ofir Weber, Mirela Ben-Chen and Craig Gotsman

CS 176 WINTER 2011

27