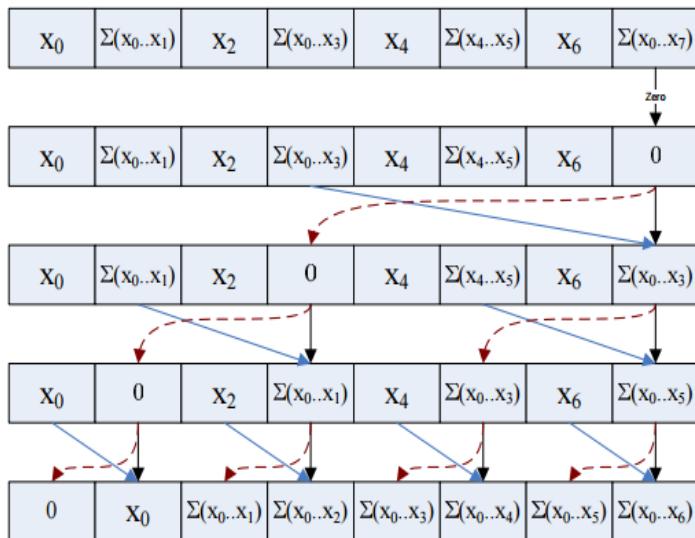
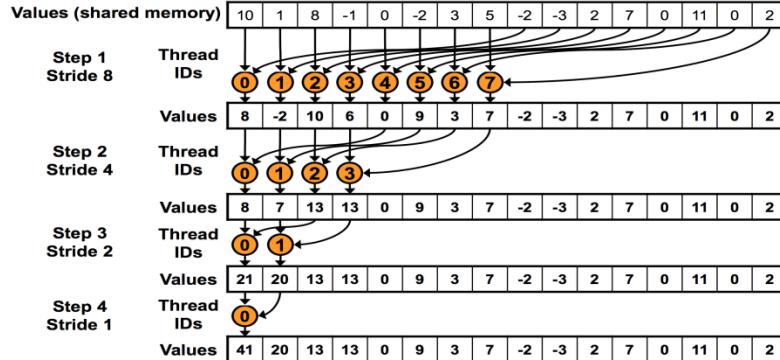


CS 179: GPU Programming

Lecture 8

Last time



- GPU-accelerated:
 - Reduction
 - Prefix sum
 - Stream compaction
 - Sorting (quicksort)

2	5	1	4	6	3
---	---	---	---	---	---

0	1	0	1	1	0
---	---	---	---	---	---

0	1	1	2	3	3
---	---	---	---	---	---

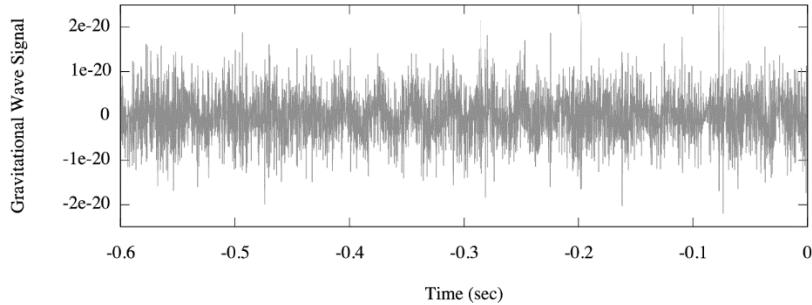
5	4	6
---	---	---

Today

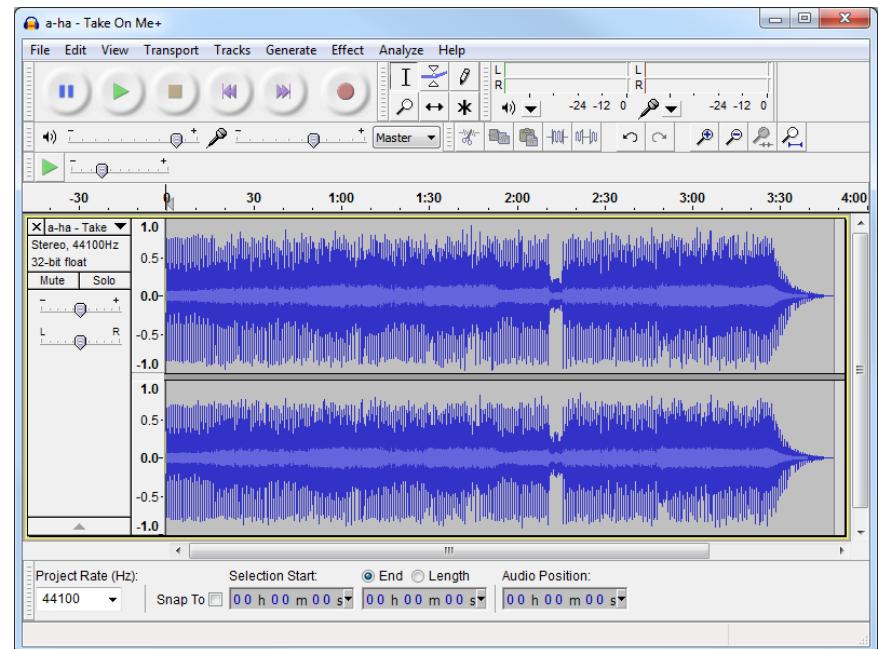
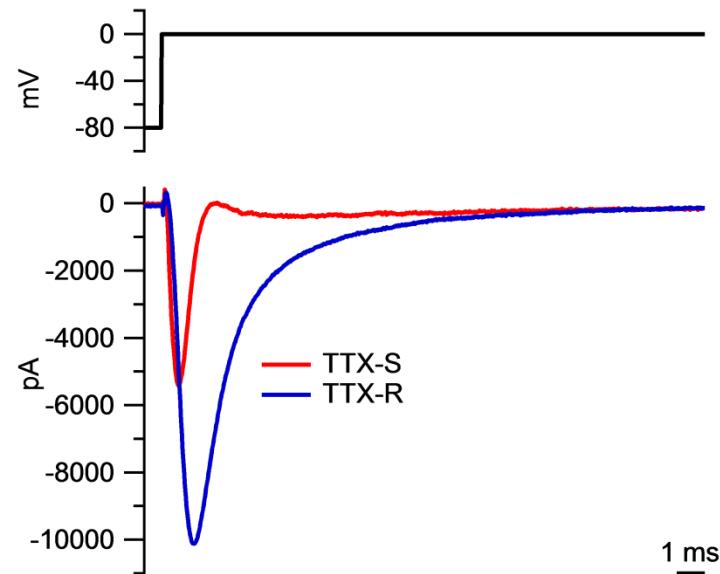
- GPU-accelerated Fast Fourier Transform
- cuFFT (FFT library)
- Don't worry about the math and even algorithmic details TOO much. This lecture should be a case study in why you shouldn't re-invent the wheel (implement what a library already does for you)

Signals (again)

Example Inspiral Gravitational Waves with Noise



Sodium current from Rat small DRG neuron



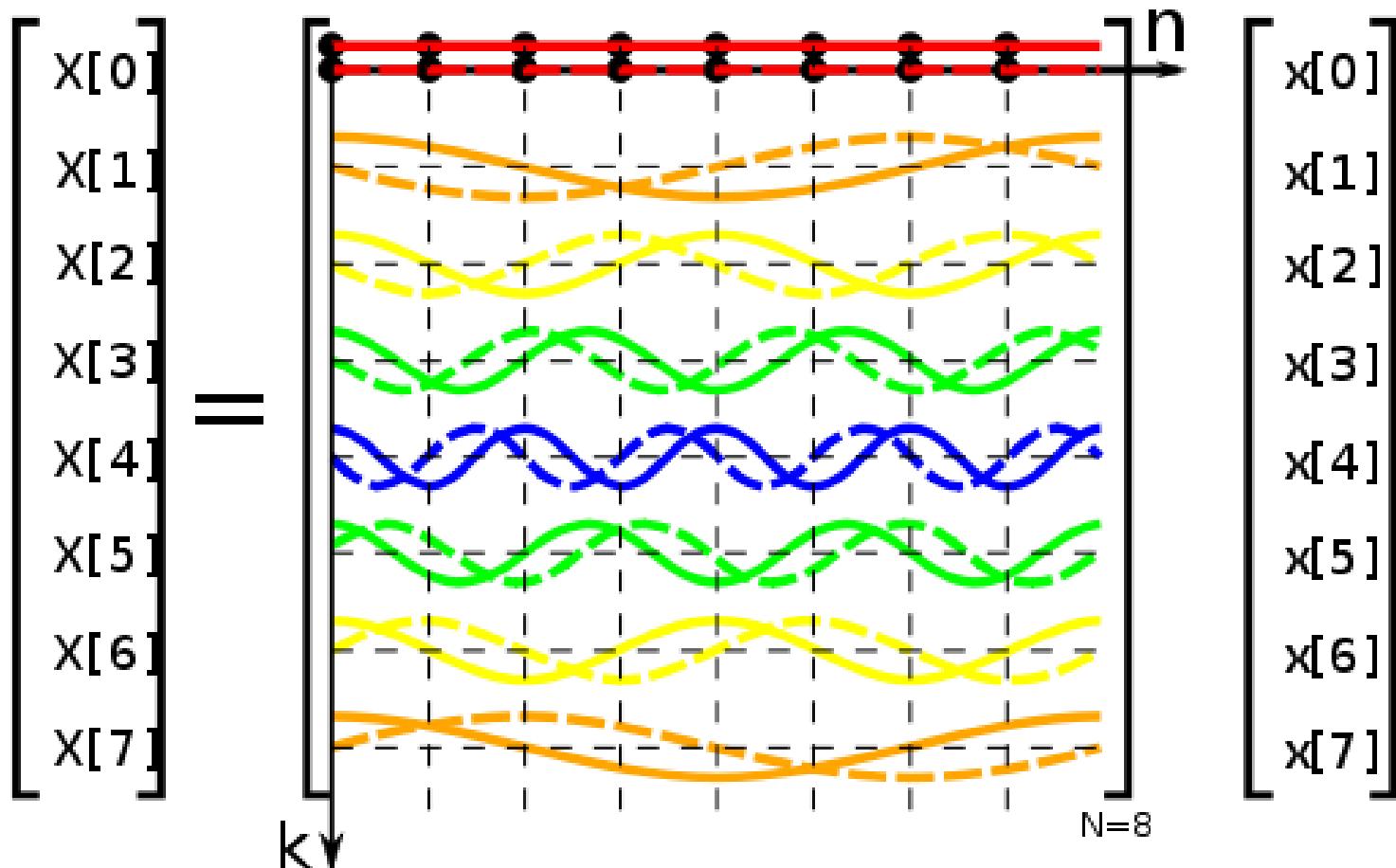
“Frequency content”

- What frequencies are present in our signals?

Discrete Fourier Transform (DFT)

$$W = \frac{1}{\sqrt{N}} \begin{bmatrix} 1 & 1 & 1 & 1 & \dots & 1 \\ 1 & \omega & \omega^2 & \omega^3 & \dots & \omega^{N-1} \\ 1 & \omega^2 & \omega^4 & \omega^6 & \dots & \omega^{2(N-1)} \\ 1 & \omega^3 & \omega^6 & \omega^9 & \dots & \omega^{3(N-1)} \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & \omega^{N-1} & \omega^{2(N-1)} & \omega^{3(N-1)} & \dots & \omega^{(N-1)(N-1)} \end{bmatrix},$$

- Given signal $\vec{x} = (x_1, \dots, x_N)$ over time, $\omega = e^{-2\pi i/N}$
 $\vec{y} = W\vec{x}$ represents DFT of \vec{x}
 - Each row of W is a complex sine wave
 - Each row multiplied with \vec{x} - inner product of wave with signal
 - Corresponding entries of \vec{y} - “content” of that sine wave!



Solid line = real part

Dashed line = imaginary part

Discrete Fourier Transform (DFT)

- Alternative formulation:

$$X_k \stackrel{\text{def}}{=} \sum_{n=0}^{N-1} x_n \cdot e^{-2\pi i kn/N}, \quad k \in \mathbb{Z}$$

- X_k - values corresponding to wave k

- Periodic – calculate for $0 \leq k \leq N - 1$

Discrete Fourier Transform (DFT)

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 - Periodic – calculate for $0 \leq k \leq N - 1$
- Naive runtime: $O(N^2)$
 - Sum of N iterations, for N values of k

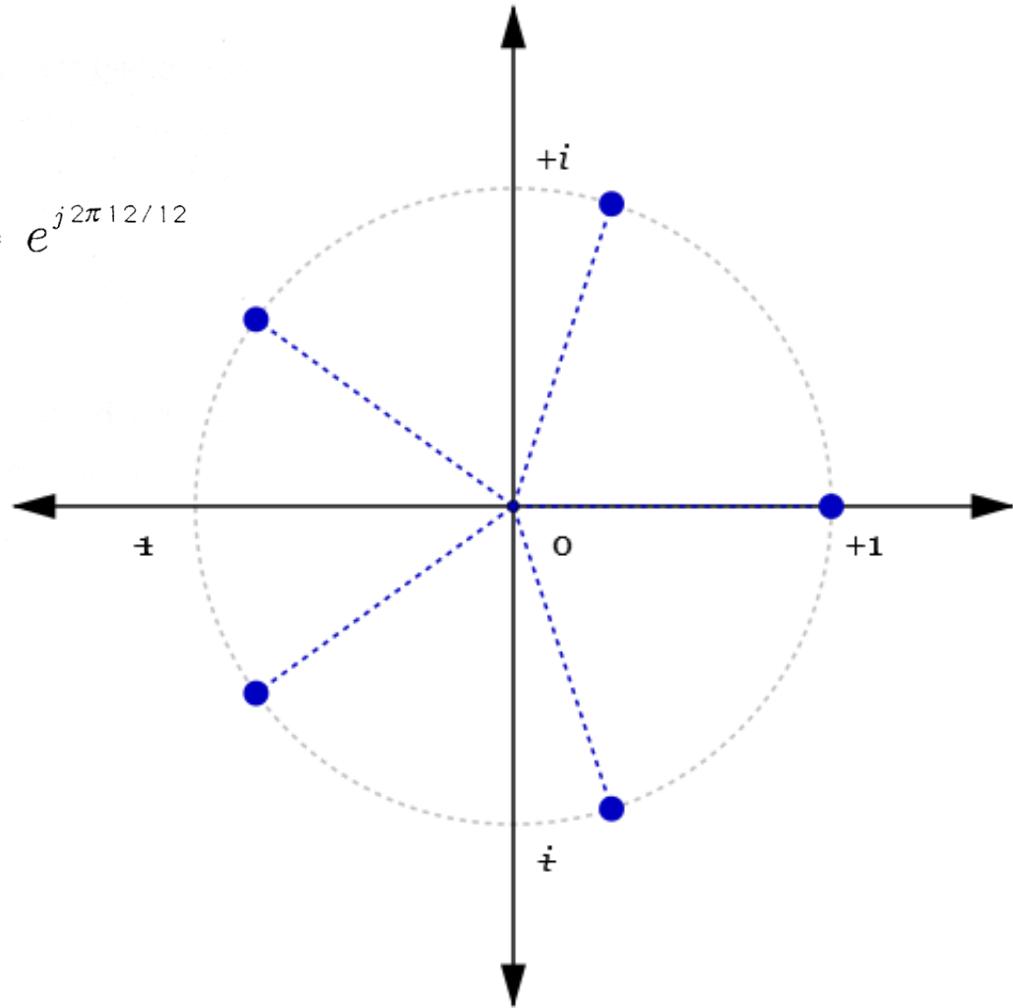
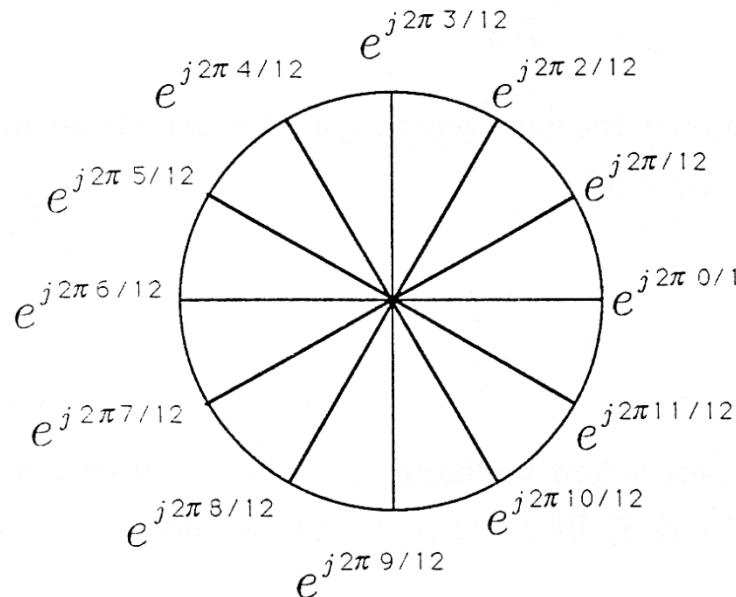
Discrete Fourier Transform (DFT)

- Alternative formulation:

$$X_k \stackrel{\text{def}}{=} \sum_{n=0}^{N-1} x_n \cdot e^{-2\pi i k n / N}, \quad k \in \mathbb{Z}$$

- X_k - values corresponding to wave k
 - Periodic – calculate for $0 \leq k \leq N - 1$
- Naive runtime: $O(N^2)$
 - Sum of N iterations, for N values of k

Roots of unity



Discrete Fourier Transform (DFT)

- Alternative formulation:

$$X_k \stackrel{\text{def}}{=} \sum_{n=0}^{N-1} x_n \cdot e^{-2\pi i k n / N}, \quad k \in \mathbb{Z}$$

– X_k - values corresponding to wave k

- Periodic – calculate for $0 \leq k \leq N - 1$

Number of distinct values: **N**, not **N^2 !**

(Proof)

- Breakdown (assuming N is power of 2):
 - (Let $\omega_N = e^{-2\pi i/N}$, smallest root of unity)

$$\sum_{n=0}^{N-1} x_n \omega_N^{kn}$$

(Proof)

- Breakdown (assuming N is power of 2):
 - (Let $\omega_N = e^{-2\pi i/N}$, smallest root of unity)

$$\sum_{n=0}^{N-1} x_n \omega_N^{kn}$$

$$= \sum_{n=0}^{N/2-1} x_{(2n)} \omega_N^{k(2n)} + \sum_{n=0}^{N/2-1} x_{(2n+1)} \omega_N^{k(2n+1)}$$

(Proof)

- Breakdown (assuming N is power of 2):
 - (Let $\omega_N = e^{-2\pi i/N}$, smallest root of unity)

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$$= \sum_{n=0}^{N/2-1} x_{(2n)} \omega_N^{k(2n)} + \omega_N \sum_{n=0}^{N/2-1} x_{(2n+1)} \omega_N^{k(2n)}$$

(Proof)

- Breakdown (assuming N is power of 2):
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$$= \sum_{n=0}^{N/2-1} x_{(2n)} \omega_{N/2}^{kn} + \omega_N \sum_{n=0}^{N/2-1} x_{(2n+1)} \omega_{N/2}^{kn}$$

(Proof)

- Breakdown (assuming N is power of 2):
 - (Let $\omega_N = e^{-2\pi i/N}$, smallest root of unity)

$$\sum_{n=0}^{N-1} x_n \omega_N^{kn}$$

$$= \sum_{n=0}^{N/2-1} x_{(2n)} \omega_N^{k(2n)} + \sum_{n=0}^{N/2-1} x_{(2n+1)} \omega_N^{k(2n+1)}$$

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$$= \sum_{n=0}^{N/2-1} x_{(2n)} \omega_{N/2}^{kn} + \omega_N \sum_{n=0}^{N/2-1} x_{(2n+1)} \omega_{N/2}^{kn}$$

DFT of x_n , even n!

DFT of x_n , odd n!

(Divide-and-conquer algorithm)

```
Recursive-FFT(Vector x):
```

```
    if x is length 1:
```

```
        return x
```

```
    x_even <- (x0, x2, ..., x_(n-2) )
```

```
    x_odd <- (x1, x3, ..., x_(n-1) )
```

```
    y_even <- Recursive-FFT(x_even)
```

```
    y_odd <- Recursive-FFT(x_odd)
```

```
    for k = 0, ..., (n/2)-1:
```

```
        y[k]           <- y_even[k] + wk * y_odd[k]
```

```
        y[k + n/2]    <- y_even[k] - wk * y_odd[k]
```

```
    return y
```

(Divide-and-conquer algorithm)

```
Recursive-FFT(Vector x):
```

```
    if x is length 1:  
        return x
```

```
    x_even <- (x0, x2, ..., x_(n-2) )  
    x_odd <- (x1, x3, ..., x_(n-1) )
```

```
    y_even <- Recursive-FFT(x_even)           ← T(n/2)  
    y_odd <- Recursive-FFT(x_odd)            ← T(n/2)  
    for k = 0, ..., (n/2)-1:                 ← O(n)
```

```
        y[k]      <- y_even[k] + wk * y_odd[k]  
        y[k + n/2] <- y_even[k] - wk * y_odd[k]
```

```
    return y
```

Runtime

- Recurrence relation:
 - $T(n) = 2T(n/2) + O(n)$

$O(n \log n)$ runtime! *Much better than $O(n^2)$*

- (Minor caveat: N must be power of 2)
 - Usually resolvable

Parallelizable?

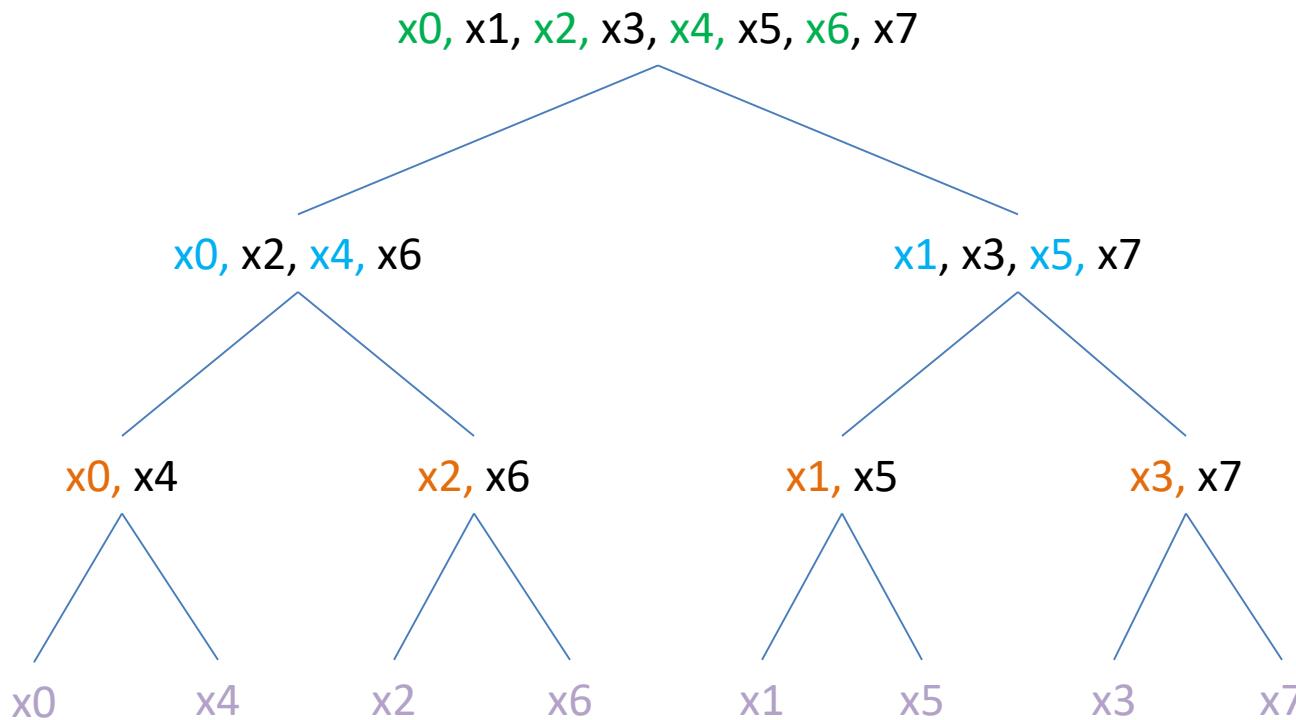
- $O(n^2)$ algorithm certainly is!

```
for k = 0,...,N-1:  
    for n = 0,...,N-1:  
        ...
```

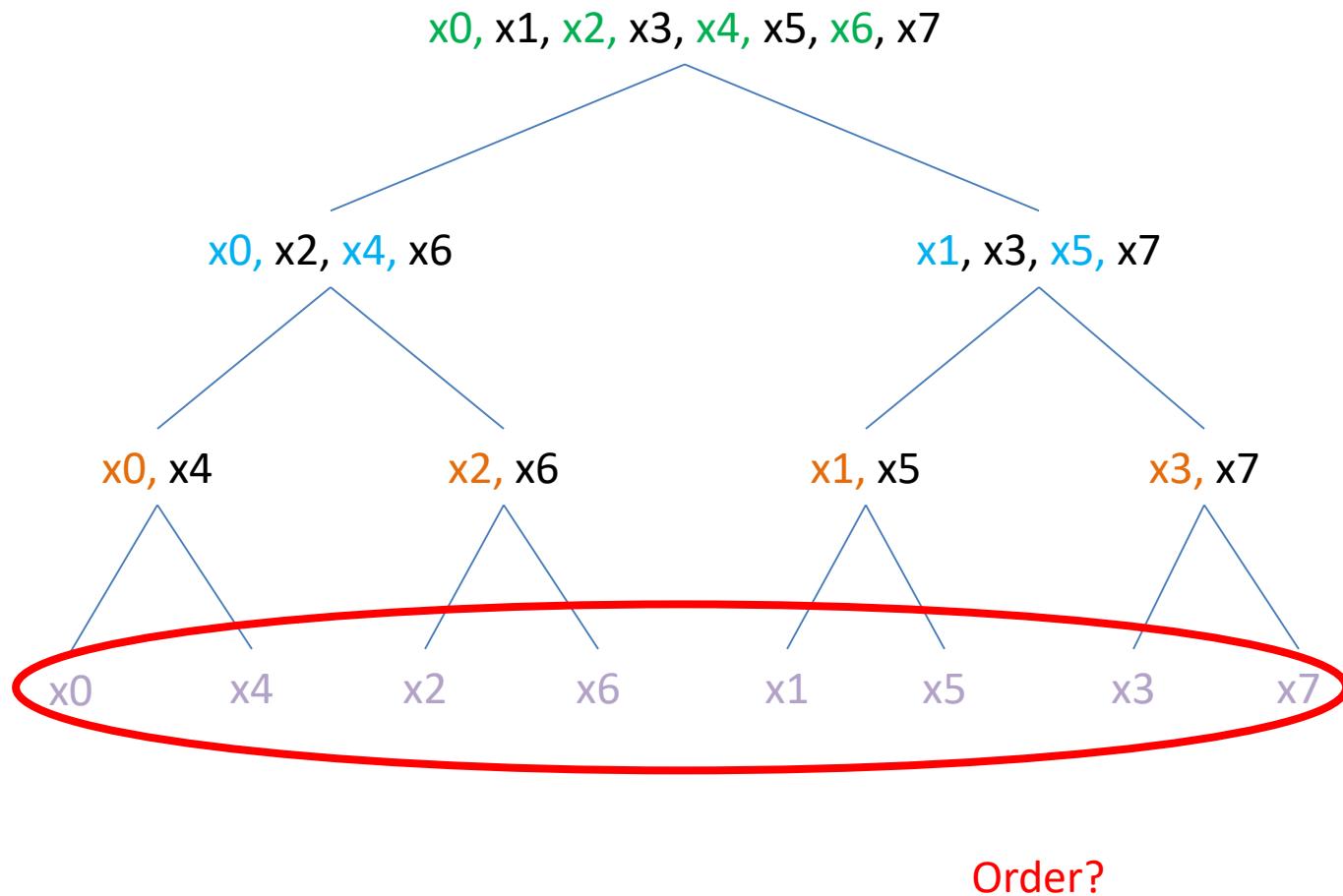
$$X_k \stackrel{\text{def}}{=} \sum_{n=0}^{N-1} x_n \cdot e^{-2\pi i kn/N}$$

- Sometimes parallelization outweighs runtime!
 - (N-body problem, ...)

Recursive index tree



Recursive index tree



Bit-reversal order

0	000
4	100
2	010
6	110
1	001
5	101
3	011
7	111

Bit-reversal order

0	000	reverse of...	000	0
4	100		001	1
2	010		010	2
6	110		011	3
1	001		100	4
5	101		101	5
3	011		110	6
7	111		111	7

(Divide-and-conquer algorithm review)

Recursive-FFT(Vector x):

```
if x is length 1:
```

```
    return x
```

```
x_even <- (x0, x2, ..., x_(n-2) )
```

```
x_odd <- (x1, x3, ..., x_(n-1) )
```

```
y_even <- Recursive-FFT(x_even)
```

$T(n/2)$

```
y_odd <- Recursive-FFT(x_odd)
```

$T(n/2)$

$O(n)$

```
for k = 0, ..., (n/2)-1:
```

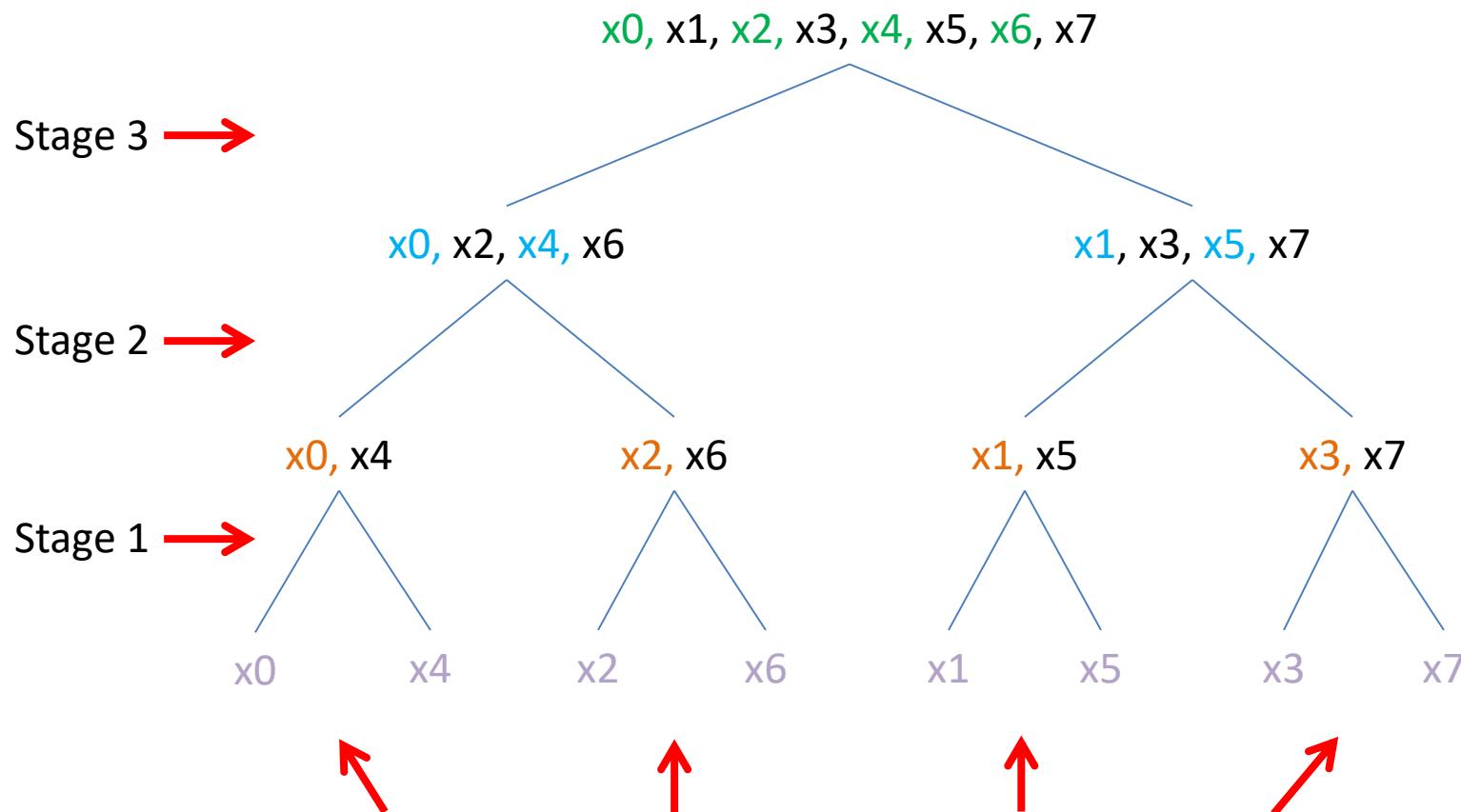


```
    y[k]      <- y_even[k] + wk * y_odd[k]
```

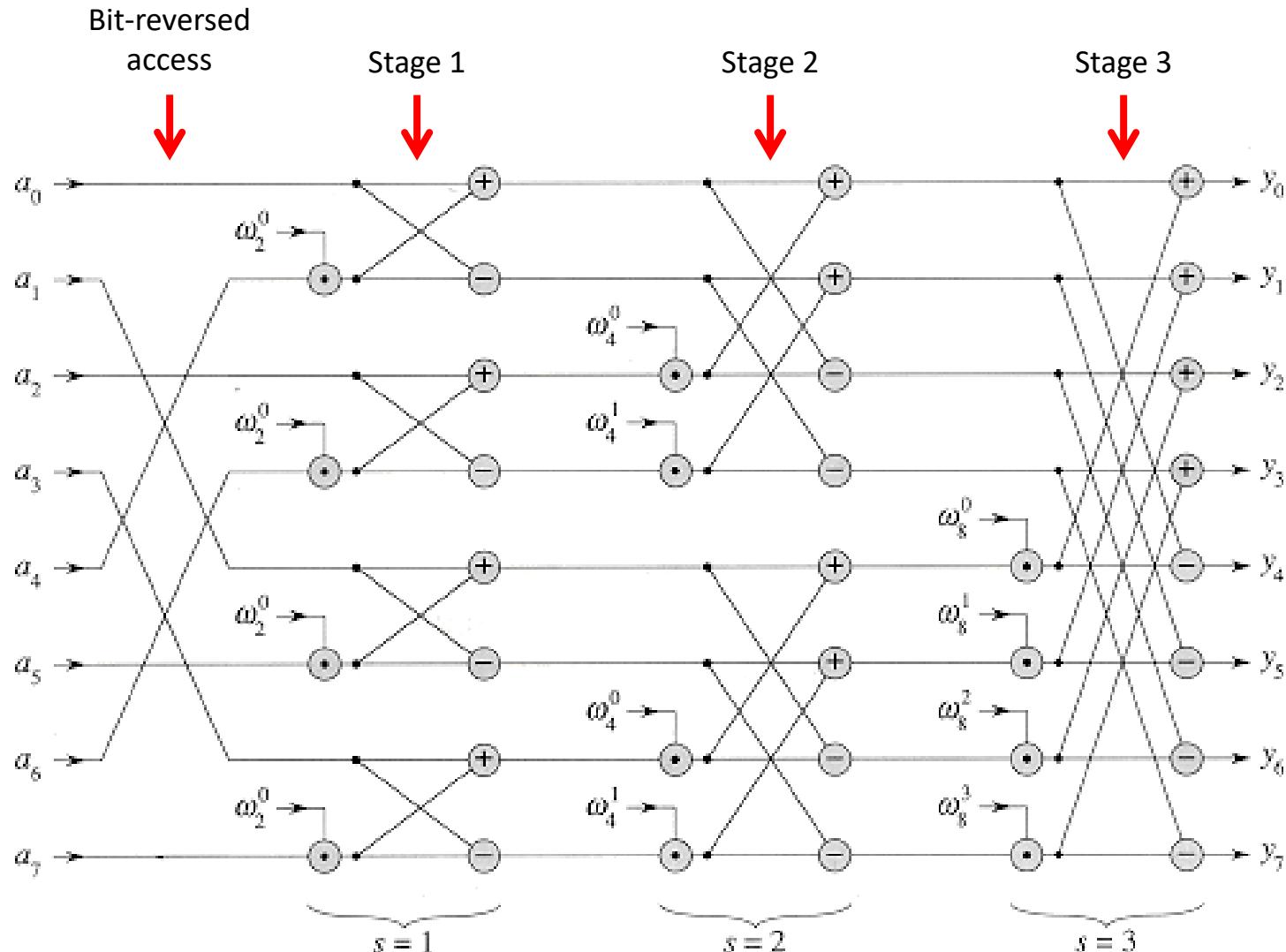
```
    y[k + n/2] <- y_even[k] - wk * y_odd[k]
```

```
return y
```

Iterative approach

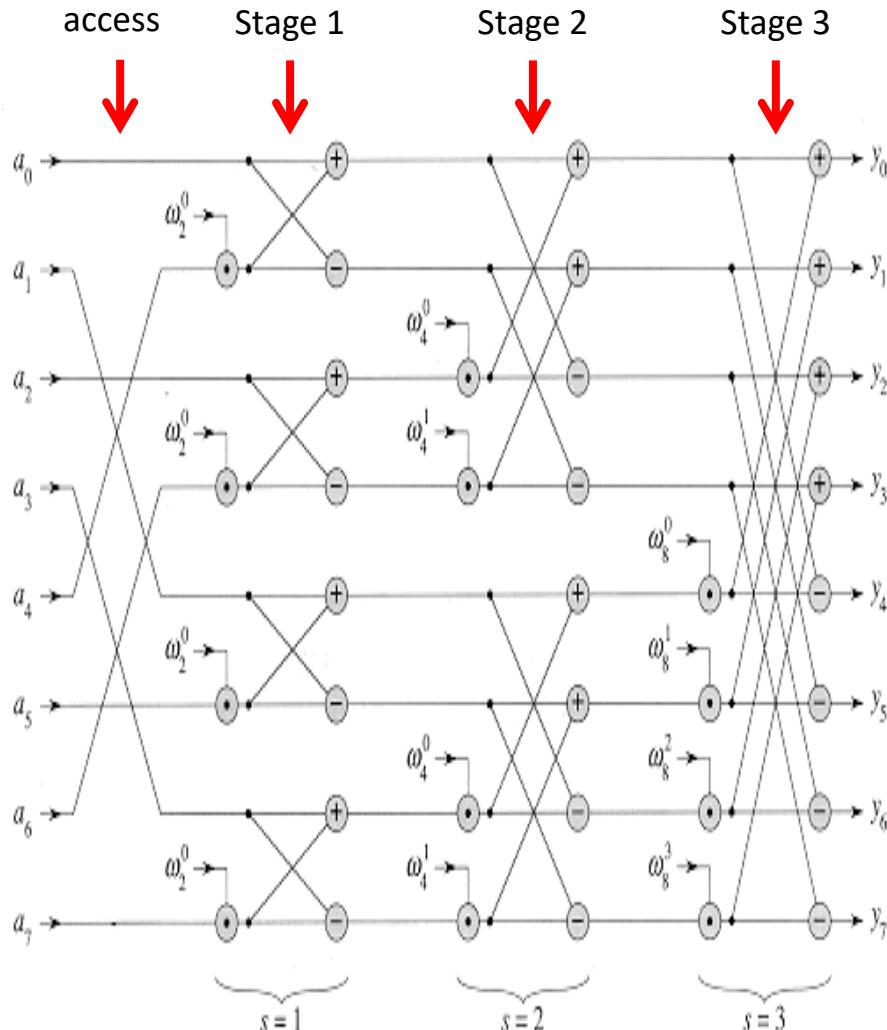


Iterative approach



Iterative approach

Bit-reversed access



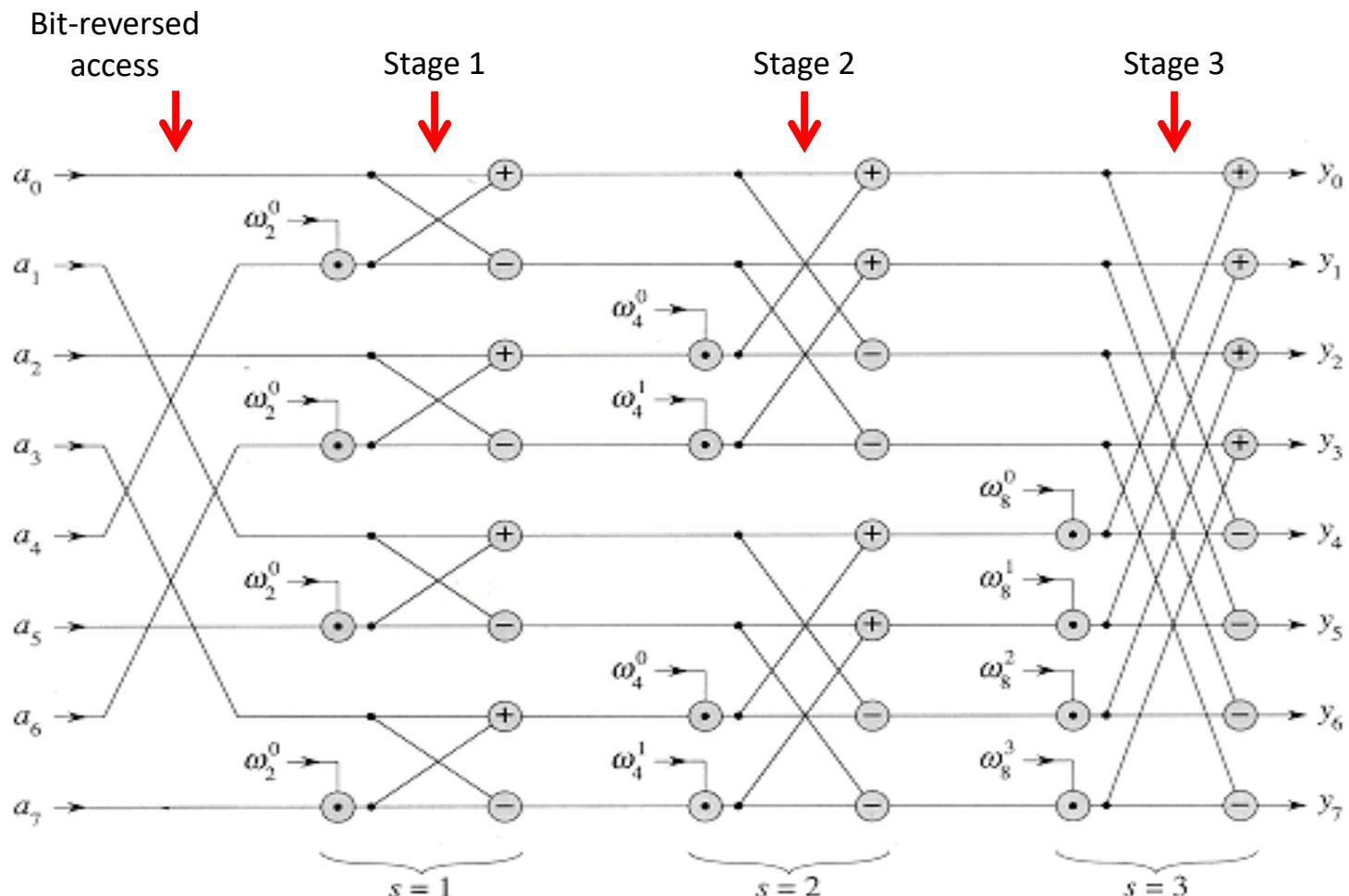
Iterative-FFT(vector x):

```

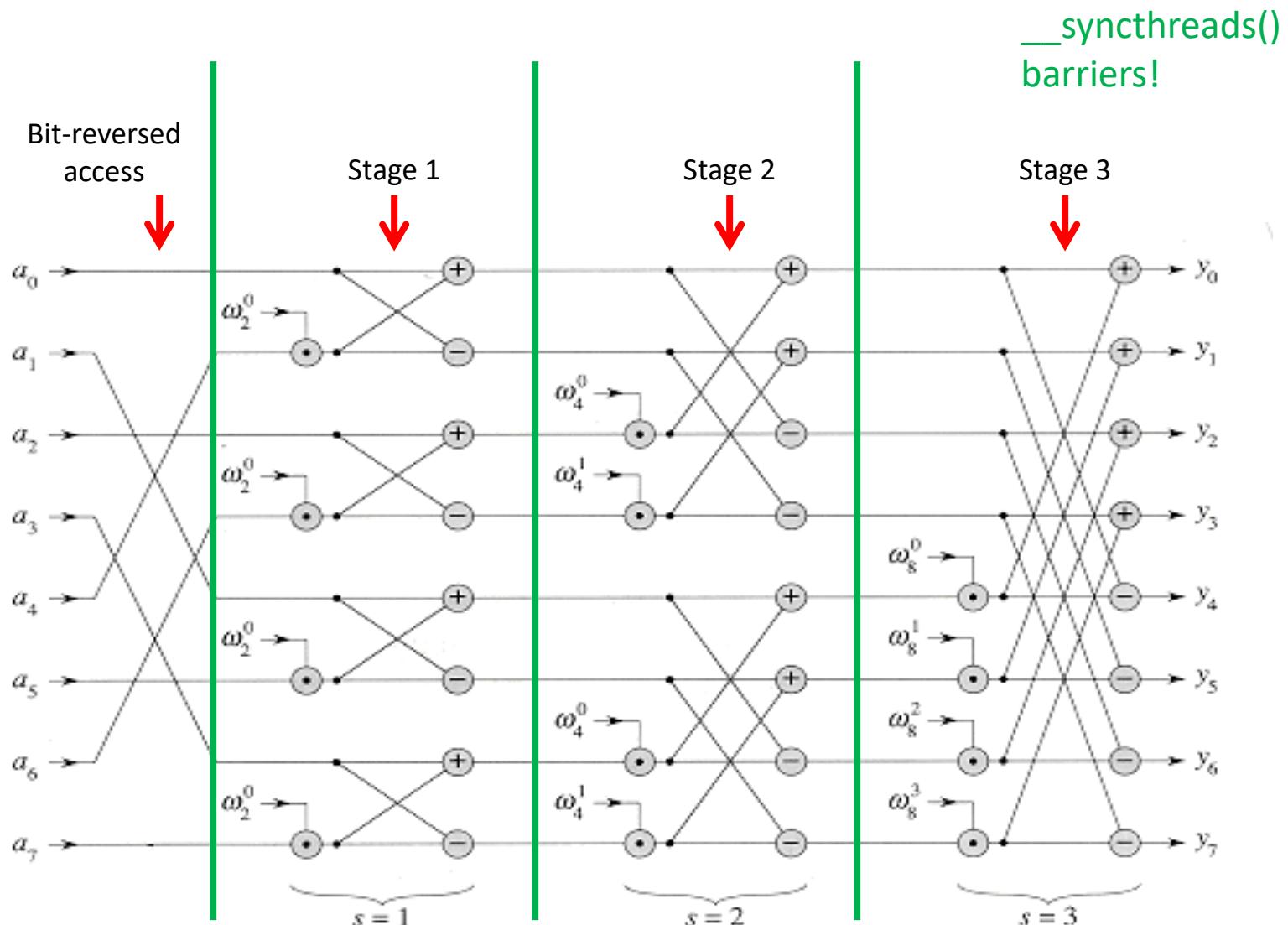
y <- (bit-reversed order x)
N <- y.length
for s = 1,2,...,lg(N):
    m <- 2s
    wn <- e2πj/m
    for k: 0 ≤ k ≤ N-1, stride m:
        for j = 0,...,(m/2)-1:
            u <- y[k + j]
            t <- (wn)j * y[k + j + m/2]
            y[k + j] <- u + t
            y[k + j + m/2] <- u - t
return y

```

CUDA approach

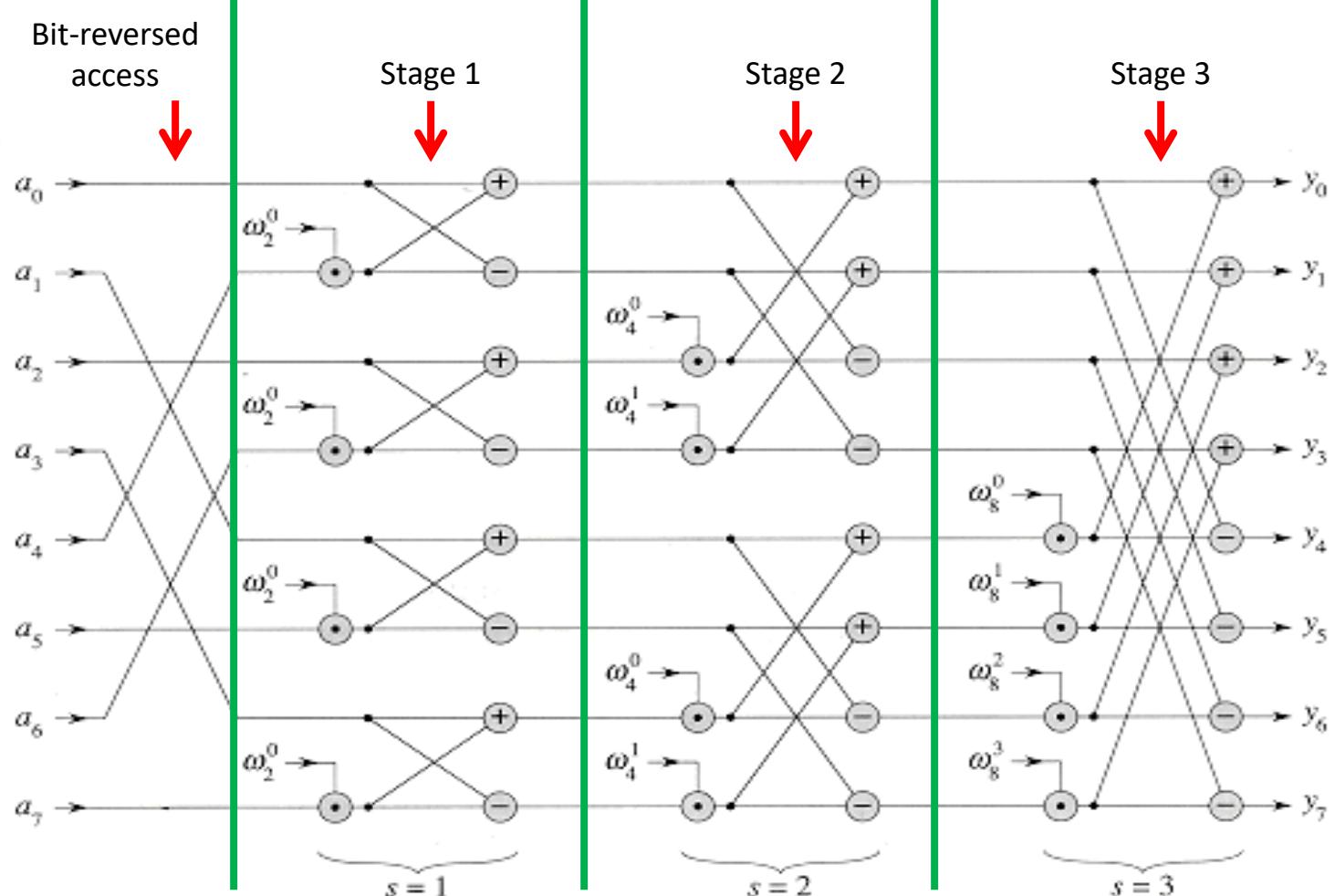


CUDA approach



CUDA approach

Non-coalesced
memory access!!



CUDA approach

Non-coalesced
memory access!!

Bit-reversed
access



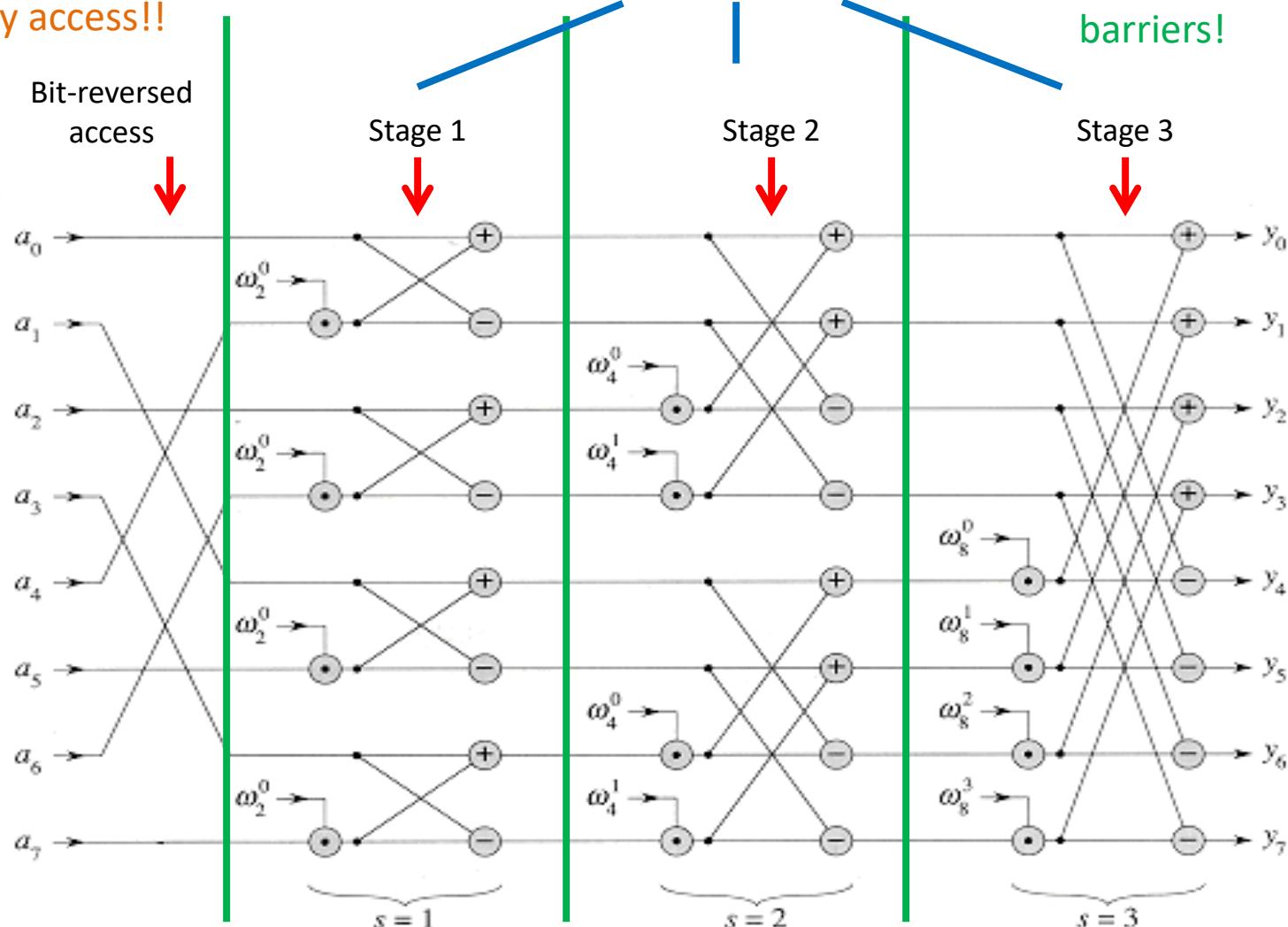
Bank conflicts!!

Stage 1

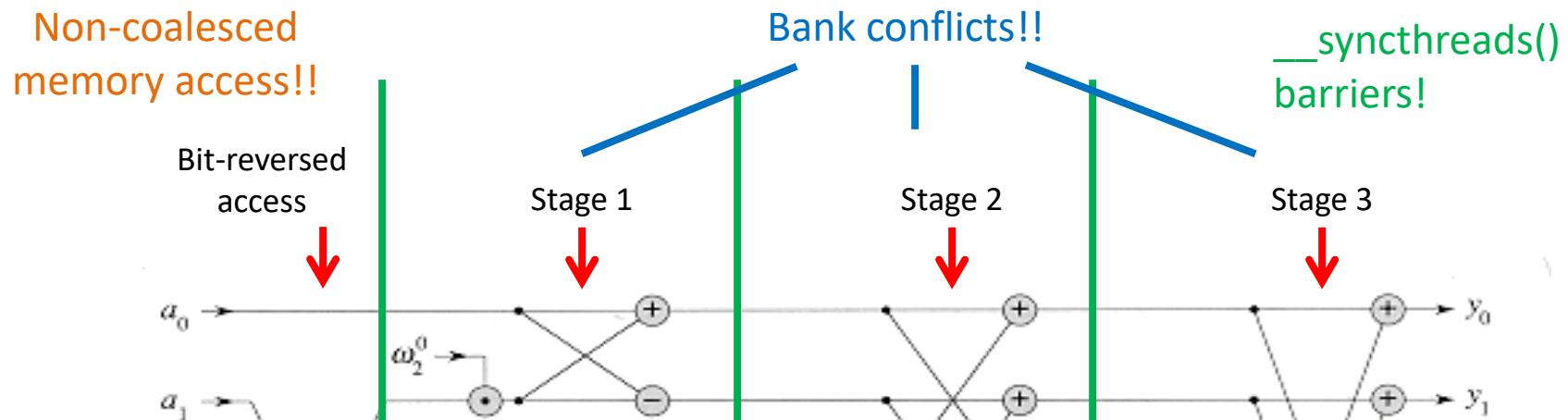
Stage 2

Stage 3

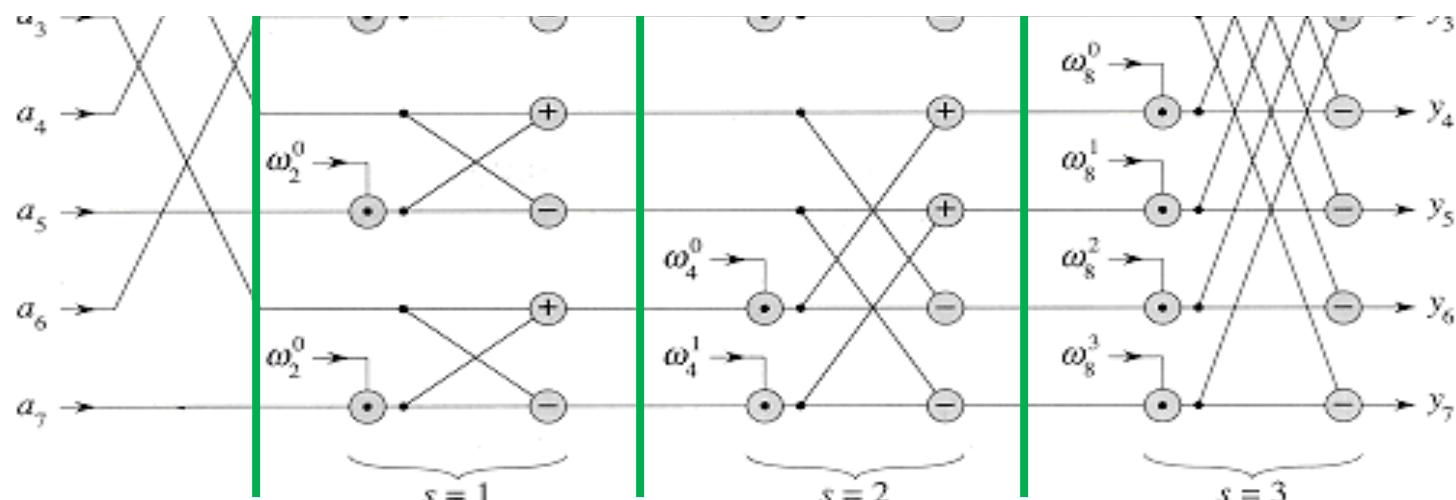
syncthreads()
barriers!



CUDA approach



THIS IS WHY WE HAVE LIBRARIES



cuFFT

- FFT library included with CUDA
 - Approximately implements previous algorithms
 - (Cooley-Tukey/Bluestein)
 - Also handles higher dimensions
 - Handles nasty hardware constraints that you don't want to think about
- Also handles inverse FFT/DFT similarly
 - Just a sign change in complex terms

$$x_n = \frac{1}{N} \sum_{k=0}^{N-1} X_k \cdot e^{i2\pi kn/N}, \quad n \in \mathbb{Z}$$

cuFFT 1D example

```
#define NX 262144

cufftComplex *data_host
    = (cufftComplex*)malloc(sizeof(cufftComplex)*NX);
cufftComplex *data_back
    = (cufftComplex*)malloc(sizeof(cufftComplex)*NX);

// Get data...

cufftHandle plan;
cufftComplex *data1;
cudaMalloc((void**)&data1, sizeof(cufftComplex)*NX);
cudaMemcpy(data1, data_host, NX*sizeof(cufftComplex), cudaMemcpyHostToDevice);

/* Create a 1D FFT plan. */
int batch = 1; // Number of transforms to run
cufftPlan1d(&plan, NX, CUFFT_C2C, batch);

/* Transform the first signal in place. */
cufftExecC2C(plan, data1, data1, CUFFT_FORWARD);

/* Inverse transform in place. */
cufftExecC2C(plan, data1, data1, CUFFT_INVERSE);

cudaMemcpy(data_back, data1, NX*sizeof(cufftComplex), cudaMemcpyDeviceToHost);
```

Correction:
Remember to use
`cufftDestroy(plan)`
when finished with
transforms

cuFFT 3D example

```
#define NX 64
#define NY 64
#define NZ 128

cufftComplex *data_host
    = (cufftComplex*)malloc(sizeof(cufftComplex)*NX*NY*NZ);
cufftComplex *data_back
    = (cufftComplex*)malloc(sizeof(cufftComplex)*NX*NY*NZ);

// Get data...

cufftHandle plan;
cufftComplex *data1;
cudaMalloc((void**)&data1, sizeof(cufftComplex)*NX*NY*NZ);
cudaMemcpy(data1, data_host, NX*NY*NZ*sizeof(cufftComplex), cudaMemcpyHostToDevice);

/* Create a 3D FFT plan. */
cufftPlan3d(&plan, NX, NY, NZ, CUFFT_C2C);

/* Transform the first signal in place. */
cufftExecC2C(plan, data1, data1, CUFFT_FORWARD);

/* Inverse transform in place. */
cufftExecC2C(plan, data1, data1, CUFFT_INVERSE);

cudaMemcpy(data_back, data1, NX*NY*NZ*sizeof(cufftComplex), cudaMemcpyDeviceToHost);
```

Correction:
Remember to use
cufftDestroy(plan)
when finished with
transforms

Remarks

- As before, some parallelizable algorithms don't easily “fit the mold”
 - Hardware matters more!
- Some resources:
 - Introduction to Algorithms (Cormen, et al), aka “CLRS”, esp. Sec 30.5
 - “An Efficient Implementation of Double Precision 1-D FFT for GPUs Using CUDA” (Liu, et al.)